Computer Architecture I Midterm I

Chinese Name:

Pinyin Name:

E-Mail ... @shanghaitech.edu.cn:

Question	Points	Score
1	11	
2	6	
3	16	
4	19	
5	48	
Total:	100	

- This test contains 8 numbered pages, including the cover page. The back of each page is blank and can be used for scratch-work, but will not be looked at for grading.
- Put your pinyin name on the top of every page.
- Please turn **off** all cell phones, smartwatches, and other mobile devices. Remove all hats and headphones. Put everything in your backpack. Place your backpacks, laptops and jackets under your seat.
- You have 85 minutes to complete this exam. The exam is closed book; no computers, phones, or calculators are allowed. You may use one A4 page (front and back) of notes in addition to the provided green sheet.
- The estimated time needed for each of the 5 topics is given in parenthesis. The total estimated time is 75 minutes.
- There may be partial credit for incomplete answers; write as much of the solution as you can. We will deduct points if your solution is far more complicated than necessary. When we provide a blank, please fit your answer within the space provided.

2

4

- 1. Various Questions (12 min)
- (a) Name 6 Great Ideas in Computer Architecture.

(b) How would J-type instructions be affected (in terms of their "reach") if we relaxed the requirement that instructions be placed on word boundaries, and instead allow them to be placed anywhere?

(c) You have a program that can achieve almost a 20x speedup with millions of processors, so what is the percent of the parallel portion of its workload? Show how you got to your result!

		(c)			
(d)	(d) Put the following (not exhaustive list) in chronological order. We've started it for you				
		Code and Data from various places are stitched together.			
	Static, code, and global space are reserved/initialized in memory.				
	1 A student is assigned a homework that implements a prime search.				
	Execution begins at main.				
	MAL is translated into TAL.				
	The student writes his or her code in C.				
	Link tables are produced.				
		The student's C code is translated into MIPS.			
		Links are "edited"			

4

- 2. Suppose for questions 2 (a)-(c) that we were to modify the MIPS ISA so that it exposed 50 registers instead of 32, and adjusted the field widths of our R, I and J instruction formats to be able to address all the registers, but did not change the size of the opcode or shamt fields. Registers and instructions will remain 4 bytes wide. (5 min) 2 (a) At most how many instructions can a single beq instruction now reach? (a) _____ (b) How many more addresses can now be reached from a jal instruction? |2|(b)_____ 2 (c) How many different R-type instructions can we now have? (c)_____ 3. Number Representation (12min) 4 (a) Suppose a is an 8-bit signed integer represented as $a_{hex} = 0$ xBC, then its binary representation is $a_{two} =$ _____, its decimal representation is $a_{ten} =$ _____. 4 (b) For an 12-bit value, two's complement integer, what are the largest AND smallest value you can represent in decimal?
 - (c) Assume an 8-bit two's complement machine on which all operators are performed on 8bit registers. Answer the results of the following operations in hexadecimal. Assume that subtraction is done with SUBU and addition is done with ADDU.

a	6A - 89	(hex) (hex)
b	CA + 16	(hex) (hex)

(d) Fill in the blank so that the function mod32 will return the remainder of x when divided by 32. The first blank should be a **bitwise** operator, and the second blank should be a single **decimal** number:

```
unsigned int mod32( unsigned int x ) {
   return x _____;
}
```

|2|

4. C Programming (15 min)

We wish to implement a *nibble* (4-bit) array, where we can read and write a particular *nibble*. Normally for read/write array access, we would just use bracket notation (e.g., x = A[5]; A[5] = y;), but since a nibble is smaller than the smallest datatype in C, we have to design our own **make_nibble()**, **set_nibble()** and **get_nibble()** functions. To bring you to the *C of Madness*, we require you **to complete all the blanks below in C in one line**. There is a 25% point deduction of a sub-question where you use **if/else** or the **?/:** format. We'll use the following typedefs to make our job easier.

```
/* If it is a single nibble, value is in least significant
    nibble. */
typedef uint8_t nibble_t;
```

E.g., imagine a nibble array A with 2 nibbles (1 byte):

```
A[0] = 0x3f; // initialization
get_nibble(A, 0); // return 0xf
get_nibble(A, 1); // return 0x3
set_nibble(A, 0, 0x34) // set the 0st nibble to 0x4
get_nibble(A, 0); // return 0x4
set_nibble(A, 1, 0xed) // set the 1st nibble to 0xd
get_nibble(A, 1); // return 0xd
```

(a) To make things easier, we require that the length of a nibble array is always a power of
2. So you may complete the macro definition to facilitate the multiplication by 2. e.g.,
TWICE(3) gives 6.

```
/* Calculate the multiplication by 2 below */
#define TWICE(X) ______
```

(b) Suppose we have declared a pointer **nibble** of nibble array.

nibble_t *nibble; /* pointer of nibble array. */

Now we need to allocate 4 nibbles for the declared pointer. You may 1) complete the parameter list, 2) write **make_nibble()** in C in one line (you don't need to handle exceptions), 3) complete the function call.

```
void make_nibble(______, uint32_t length) {
   /* one line of code below */
}
/* somewhere in main... */
make_nibble(______, TWICE(2));
```

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(c) You may write **set_nibble**() in C in as one command. When we say write item into head[index], we are to write the four bits on the right end of the item into head[index].

```
void set_nibble(nibble_t *head, uint32_t index, uint8_t item) {
    /* one line of code below */
```

```
}
```

(d) You may write **get_nibble**() in C in one line.

```
uint8_t get_nibble(nibble_t *head, uint32_t index) {
   /* one line of code below */
```

}

- 5. Question: Binary Search in MIPS: ((a) 4 min; (b) 8 min; (c-i) 10 min; (j) 8 min; total: 30 min)
- (a) First of all, let's review the binary search algorithm. The binary search algorithm finds the position of a target value within a sorted array (smallest to biggest). It is efficient for sorted datastructures that are stored continuously in memory.

We've provided you with a C function in the space below. Fill in the code at places marked with (1) and (2).

```
int binary_search(int *data, int n, int value)
{
   int left = 0;
   int right = n-1;
   int mid ;
   while (left < right)</pre>
   {
      mid = (left + right) >>1;
                               ____)
                                                     /* (1) */
      if(____
      {
         left = mid + 1;
      } else
      {
                                                     /* (2) */
      }
   }
   if (data[left]==value) return left;
   return -1;
}
```

(b) Now that you've warmed up on the C version of this code, let's convert it into MIPS code! In the following code, each element in array is 32-bit integer. The argument register \$a0 is the pointer to the first element in memory. The argument register \$a1 a 32-bit integer which indicates the number of elements in array. The value you need to find out from array is in \$a2. You need to provide the index in \$v0 if the value of \$a2 is in the array, otherwise set it to -1. Fill in the code at (3) - (8).

```
binary_search:
li $t0,0
addu $t1, $a1, -1
LOOP:
                                                          # (3)
beg $t2, $0, ENDLOOP
add $t3, $t0, $t1
sra $t4,
                                                          # (4)
                                                          # (5)
add $a3, $t3, $a0
lw $t3, 0($a3)
slt $t2, $t3, $a2
                                                          # (6)
add $t0, $t4, 1
j NEXT
ELSE:
add $t1, $t4, $0
NEXT:
j LOOP
ENDLOOP:
mul $t3, $t0, 4
                                                          # (7)
lw $t3, 0($a3)
beq $t3, $a2, SUCCESS
li $v0, -1
j DONE
SUCCESS:
                                                          # (8)
DONE:
jr $ra
```

 $\left|2\right|$

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(c) Towards the end of the above listing there is the instruction "beq \$t3, \$a2, SUCCESS". When will the goal address be determined and, if you can tell now, what is the value?

(d) Towards the end of the above listing there is the instruction "j DONE". When will the goal address be determined and, if you can tell now, what is the value?

- (e) Towards the end of the above listing there is the instruction "jr \$ra". When will the goal address be determined and, if you can tell now, what is the value?
 - (f) The Assembly code above can be used as a function. How would you call the function and which registers would you need to fill with proper values before calling the function?
- (g) The Assembly code above can be used as a function. Why is it not using the stack? Explain in detail.

(h) The Assembly code above can be used as a function. It is not using the stack. Assuming we would have used 8 bytes of the stack space, add the instruction that is needed at the end of the function:

DONE:

(9)

jr \$ra

8

 (i) The Assembly code above contains pseudoinstructions. List all of the pseudoinstructions that were used and also which instructions they are generally replaced with (without registers).

(j) Instruction Format: Translate the assembly into machine code and vice versa.

Instruction	Code
mult \$t1, \$t2	
xor \$v0, \$a0, \$a1	
lw \$t3, -8(\$s4)	
	0x35020018