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Computer Architecture I Mid-Term I

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Question:	1	2	3	4	5	6	7	8	9	10	11	12	Total
Points:	1	3	11	11	10	12	7	16	5	10	7	7	100
Score:													

- This test contains 21 numbered pages, including the cover page, printed on both sides of the sheet.
- We will use Gradescope for grading, so only answers filled in at the obvious places will be used.
- Use the provided blank paper for calculations and then copy your answer here.
- Please turn **off** all cell phones, smartwatches, and other mobile devices. Remove all hats and headphones. Put everything in your backpack. Place your backpacks, laptops and jackets out of reach.
- Unless told otherwise always assume a 32bit machine.
- The total estimated time is 120 minutes.
- You have 120 minutes to complete this exam. The exam is closed book; no computers, phones, or calculators are allowed. You may use two A4 pages (front and back) of handwritten notes in addition to the provided green sheet.
- There may be partial credit for incomplete answers; write as much of the solution as you can. We will deduct points if your solution is far more complicated than necessary. When we provide a blank, please fit your answer within the space provided.
- Do **NOT** start reading the questions/ open the exam until we tell you so!

	3. Number Representation	
3	(a) Given the number <code>0x811F00FA</code> . It can be interpreted as:	
	a binary number:	
	four unsigned bytes:	
	four two's complement bytes:	

Email:

Solution:

3

Solution:
1000 0001 0001 1111 0000 0000 1111 1010;
129, 31, 0, 250; -127, 31, 0, -6;

(b) A quarter is a single byte split into the following fields (1 sign, 3 exponent, 4 mantissa): SEEEMMMM. It has all the properties of IEEE 754 (including denormal numbers, NaNs and $\pm \infty$) just with different ranges, precision and representations. For a quarter, the bias of the exponent is 3, and the implicit exponent for denormal numbers are -2.

What is the largest number smaller than ∞ ?

In binary	
•	

In decimal

Which negative denormal number is closest to 0?

In binary _____

In decimal

Solution: 01101111; 15.5; 10000001; $-\frac{1}{64}$.

 $\boxed{4}$ (c) What is the value of q1, q2, c, d?

Hint Rounding mode: round toward even/0.

```
1 quarter q1, q2, q3, c, d;
2 q1 = -0.25;
3 q2 = -4.0;
4 q3 = 0.125;
5 c = q1 + (q2 + q3);
6 d = (q1 + q2) + q3;
```

q1 in binary

q2 in binary

c in decimal

d in decimal

Solution: 10010000; 11010000; -4.25; -4.50.

4. C Basics

(a) Memory of C

```
1 #include <stdlib.h>
2
3 int main() {
4    static int p = 5;
5
6    char *str = _____;
7    /* some other codes, and you can skip it. */
8    return 0;
9 }
```

1. You need to allocate a string str containing p characters. Write the code above (please use malloc).

```
Solution: char *str = malloc(sizeof(char) * (p + 1));
```

2. Fill in the correct memory section based on what the given C expressions evaluate to.

&p	
&str	
str	

Solution: static, stack, heap.

- (b) Catch bugs!
 - 1. When you want to debug with GDB, what flag you will put in your compilation?

```
Solution: -g
```

2. Write down some essential commands in GDB. Example: Start your program: run/r

Set break point:

Show next line(stepping into function calls):

```
Solution: break/b, step/s
```

(c) C programming: Reverse singly linked list. For example, convert $1 \to 2 \to 3 \to NULL$ to $3 \to 2 \to 1 \to NULL$. (You may not need all of the lines)

```
1 #include <stdio.h>
 2 #include <stdlib.h>
 4 /* Definition for singly-linked list. */
 5 struct ListNode {
       int val;
 7
       struct ListNode *next;
8 };
10 /* Given the head of a singly linked list, reverse
       the list, and return the head of reversed list.*/
12 struct ListNode *reverse list(struct ListNode *head) {
       struct ListNode *prev = NULL;
13
14
       struct ListNode *curr = head;
15
       struct ListNode *next = head;
16
       while (curr) {
17
           next = next->next;
18
19
20
21
22
23
24
25
26
27
28
29
30
31
       return prev;
32 }
```

```
Solution:
curr->next = prev;
prev = curr;
curr = next;
```

5. Byte-Swap Operation

Assuming we are in a **32bit**, **little endian** system. Little Dragon receives a 4-byte integer num, he wants to swap the value of num's i^{th} byte and j^{th} byte $(i, j \in \{0, 1, 2, 3\}, i \neq j)$ to get a new number!

(a) **Idea I**: Little Dragon wants to directly retrieve the i^{th} and j^{th} byte of num, then swap them.

First of all, define a MACRO to get the i^{th} byte of num. Read the following C code, then help $Little\ Dragon$ to fill in the blank lines (Line 4 and 10) so the output should be 0x34. When defining the MACRO, use &, |, $^{^{\circ}}$, $^{^{\circ}}$

```
1 #include <stdio.h>
 2 #include <stdint.h>
 4 #define GET BYTE(num, ind)
 6 int main(){
 7
       int number, index;
 8
       int8 t byte;
 9
       number = 0x12345678;
10
                   _____; /* index is one of \{0, 1, 2, 3\} */
11
       byte = GET BYTE(number, index);
12
13
       printf("%#x\n", byte); /* should print 0x34 */
14
       return 0;
15 }
```

Write your answer above.

```
Solution: (((num) >> ((ind) << 3)) & 0xFF); 2.

Notice that there should be brackets around num and ind!
```

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(b) **Idea II**: An alternative way to fetch the i^{th} byte is *Union*. Little Dragon wrote the following code, but he is a little confused about the concept of little endian and big endian. Help him answer the questions below!

```
1 #include <stdio.h>
 2 #include <stdint.h>
 4 /* Tip on union: data type that stores its members
      in the same memory location */
 6 typedef union {
 7
       struct {
 8
           uint8 t byte0;
 9
           uint8 t byte1;
10
           uint8 t byte2;
11
           uint8 t byte3;
12
       } bytes;
13
       int all bits;
14 } MyInt;
15
16 int main() {
17
       MyInt intA;
18
       intA.all bits = 0x12345678;
19
       printf("%#x, %#x\n", intA.bytes.byte1, intA.bytes.byte3);
20
       return 0;
21 }
```

What is the expected output (in hexadecimal format) of Line 19:

- if the system is **little endian**?
- if the system is **big endian**?

```
Solution:
0x56, 0x12;
0x34, 0x78.
```

(c) **Idea III**: Little Dragon is fasczinated in playing with bitwise operations. He wrote the following function in C.

```
1 void byte_xor(int num, int a, int b) {
2    char *ret_val = (char *) #
3
4    ret_val[b] ?? ret_val[a];
5    ret_val[a] ?? ret_val[b];
6    ret_val[b] ?? ret_val[a];
7
8    printf("%#x\n", num);
9 }
```

What operators are expected to substitute the ?? in Line 4, 5, and 6, such that the result of byte_xor(0x1133CCFF, 1, 3) will be 0xCC3311FF?

A. &=, &=, &=

B. &=, ^=, ^= C. |=, ^=, ~=

D. ^=, ^=, ^=

Solution: D

6. RISC-V programming

In this question, you are asked to implement a simple recursive function in RISC-V. The function takes a decimal number as input, then outputs it's octal representation encoded as decimal digits. For example, if the input to this function is 100, then the output would be 144.

The recursive function implemented in C is given below:

```
1 int find_octal(unsigned int decimal) {
2    if (decimal == 0) {
3        return 0;
4    } else {
5        return decimal % 8 + 10 * find_octal(decimal / 8);
6    }
7 }
```

A skeleton of RISC-V code is given below.

DO NOT fill in them immediately. Do some warm-ups first!

```
1 find octal:
2
       addi
               sp, sp, -8
3
       SW
               ra, 4(sp)
4
               s0, 0(sp)
       SW
5
6
       beq
               a0, x0,
7
8
                              # set s0 to something
9
                               # set a0 to something
10
11
12
       jal
               ra, # recursive call
13
14
15
       mul
               a0, t0, a0
16
                               \# a0 = ???
17
18 postamble:
19
20
                              # Restore ra
21
22
                               # restore ...
23
24
                               # restore ...
25 end:
26
       jr
               ra
```

(a) Translate the following RISC-V instructions into machine code.

```
sw ra, 4(sp) _____andi s0, a0, 7 ____
```

Solution: 0x00112223 0x00757413

(b) What is one pseudo instruction in the RISC-V code above? How can you change it into one base instruction?

Pseudo instruction:

After your change:

Solution:

jr ra

jalr x0 ra

(c) Fill in the missing code above.

```
Solution:
beq
        a0, x0, postamble
andi
        s0, a0, 7
srli
        a0, a0, 3
jal
        ra, find octal
        t0, 10 / addi
li
                          t0, x0, 10
        a0, a0, s0
add
        ra, 4(sp)
lw
lw
        s0, 0(sp)
addi
        sp, sp, 8
```

7. RISC-V Basic

(a) Write a function in RISC-V code to return 0 if the input 32-bit float is an infinite value, else a non-zero value. The input and output will be stored in a0, as usual. Do not use pseduo instructions!

is not infinity:

ret # <= Return instruction

(b) True or False.

- 1. Let a0 point to the start of an array x. lw <math>s0, 4(a0) will always load x[1] into s0.
- 2. After calling a function and having that function return, the t registers may have been changed during the execution of the function, while a registers cannot.

1	2

Solution:

- 1. False. This only holds for data types that are four bytes wide, like int or float. For data-types like char that are only one byte wide, 4(a0) is too large of an offset to return the element at index 1, and will instead return a char further down the array (or some other data beyond the array, depending on the array length).
- 2. False. a0 and a1 registers are often used to store the return value from a function, so the function can set their values to the its return values before returning. So all a registers can be used temporary registers, as specified in the green card.

8. CALL

Answer the following questions with regard to the following C program.

```
1 #include <stdio.h>
2
3 int main(int argc, char *argv[]) {
4    if (argc == (1 + 1)) {
5        printf("Hello, %s.\n", argv[1]);
6    } else {
7        printf("Goodbye.\n");
8    }
9
10    return 0;
11 }
```

- (a) Select which stage of CALL is responsible for the following actions. Please fill you answer (A, B, C or D) in the table below.
 - A. Compiler
- B. Assembler
- C. Linker
- D. Loader

- 1. Removes all pseudo instructions.
- 2. Provide the address to the string "Goodbye.\n".
- 3. Remove most duplicate instructions in the program in order to optimize the program.
- 4. Put arguments in the address of argv so that the program could read from it.
- 5. Incorporating dynamic libraries so that the program could call printf in the C standard library.
- 6. Creates the symbol table so that we can know the address to the function main in future stages.
- 7. The parser is used to determine the operator precedence in argc == (1 + 1).
- 8. Determine the jump address the if statement is jumping to.

1	2	3	4	5	6	7	8

Solution: B; C; A; D; D; B; A; B.

- (b) True or False. Please fill your answer (T or F) in the table below.
 - 1. Pseudo instructions are not allowed in the output of compiler.
 - 2. Statically-linked libraries are incorporated into the program during the load stage.
 - 3. Dynamically-linked libraries are incorporated into the program during the link stage.
 - 4. The interpreted program (like Python) runs way faster than a compiled one (like C) in most cases.

- 5. The assembler takes two passes over the code to resolve PC-Relative target addresses.
- 6. Copying arguments passed to the program onto the stack is done during the linking stage.
- 7. Assembler can always provide the correct immediate value when translating all la instructions.
- 8. Compiling stage is the one most often responsible for code optimization.

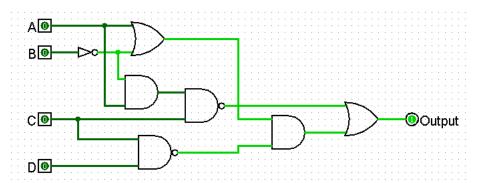
1	2	3	4	5	6	7	8

Solution: F; F; F; F; T; F; T.

9. Logic

5

(a) The circuit shown below can be simplified. Please **write** down the boolean expression that exactly corresponds to the circuit shown (no simplification). Then simplify this prepossession step by step, applying one rule at a time. Then **draw** the circuit according to the simplified boolean expression using the minimum number of **one-or two-input** logic gates.



Solution:

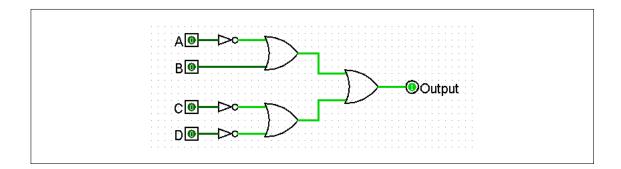
$$\overline{A\overline{B}C} + (A + \overline{B})(\overline{C}\overline{D}) = \overline{A} + B + \overline{C} + (A + \overline{B})(\overline{C} + \overline{D})$$

$$= \overline{A} + B + \overline{C} + A\overline{C} + A\overline{D} + \overline{B}\overline{C} + \overline{B}\overline{D}$$

$$= \overline{A} + B + \overline{C} + A\overline{D} + \overline{B}\overline{D}$$

$$= \overline{A} + B + \overline{C} + \overline{D}$$

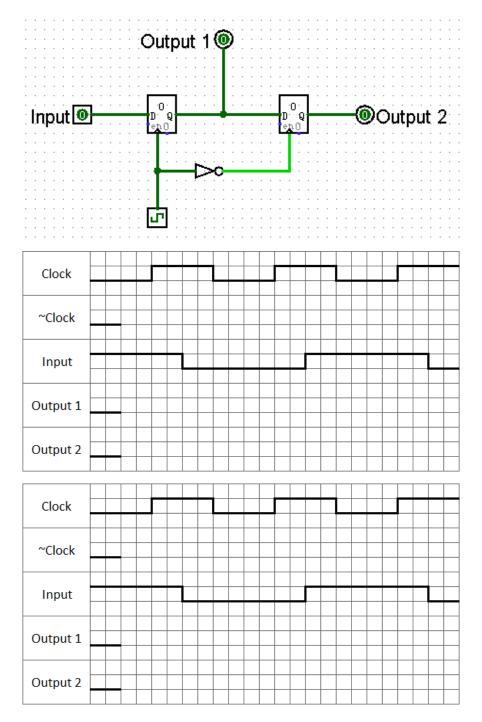
One possible circuit:

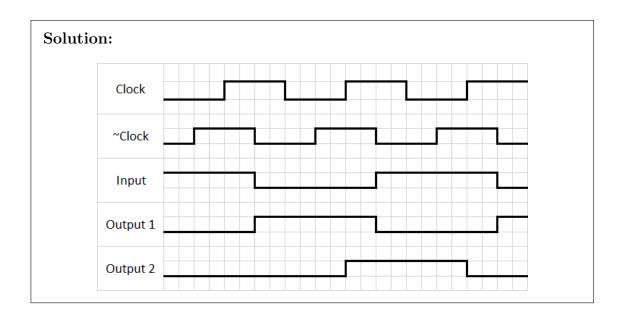


10. **SDS**

6

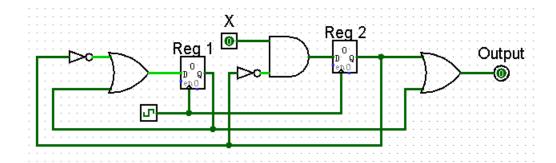
(a) Draw the Timing Diagram for the circuit below. NOT gates have a 2 ns propagation delay. For each register, the clk-to-q delay is 2 ns and setup time is 2 ns. The clock period is 8 ns, and each grid in the following diagram is a unit of 1 ns. The initial values of clock and output are given in the diagram. Use any of the two empty graphs to put in your answer (so you can re-do it). Clearly **mark your final answer** if you use more than one graph!





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(b) Consider the following circuit. Assume the clock has a frequency of 50 MHz, all gates have a propagation delay of 6 ns, X changes 10 ns after the rising edge of clk, Reg1 and Reg2 have a clk-to-q delay of 1 ns.



What is the **longest possible setup time** such that there are no setup time violations?

What is the **longest possible hold time** such that there are no hold time violations?

Solution:

The clock period is $\frac{1}{50 \times 10^6} s = 20 \ ns$.

Reg1 longest possible setup time: the path is the output of $Reg2 \rightarrow NOT \rightarrow OR$, with a delay of 1 ns + 6 ns + 6 ns =13 ns. So 20 - 13 = 7 ns.

Reg2 longest possible setup time: the path is X changes $\to AND$, with a delay of 10 ns + 6 ns = 16 ns. So 20 - 16 = 4 ns.

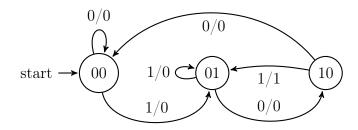
So longest setup time: min(7 ns, 4 ns) = 4 ns.

Reg1 longest possible hold time: the path is the output of $Reg1 \rightarrow OR$, with a delay of 1 ns + 6 ns = 7 ns.

Reg2 longest possible hold time: the path is the output of $Reg2 \rightarrow NOT \rightarrow AND$, with a delay of 1 ns + 6 ns + 6ns = 13 ns.

So longest hold time: min(7 ns, 13 ns) = 7 ns.

11. **FSM**



(a) Fill in the truth table for the FSM above.

state bit1	state bit0	input	next state bit1	next state bit0	output
0	0	0			
0	0	1			
0	1	0			
0	1	1			
1	0	0			
1	0	1			

state bit1	state bit0	Input	next state bit1	next state bit0	Output
0	0	0	0	0	0
0	0	1	0	1	0
0	1	0	1	0	0
0	1	1	0	1	0
1	0	0	0	0	0
1	0	1	0	1	1

(b) What does the given FSM output with the input bit string '0100101010'?

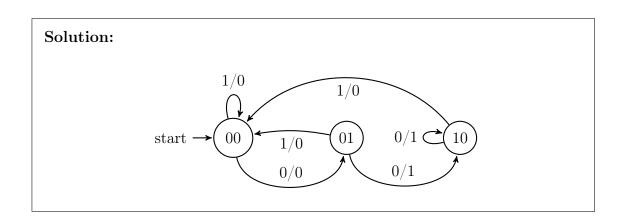
Solution: It outputs '0000001010'.

(c) What does the given FSM implement (Describe when the FSM will output 1)?

Solution: When the FSM receives '101', it outputs 1.

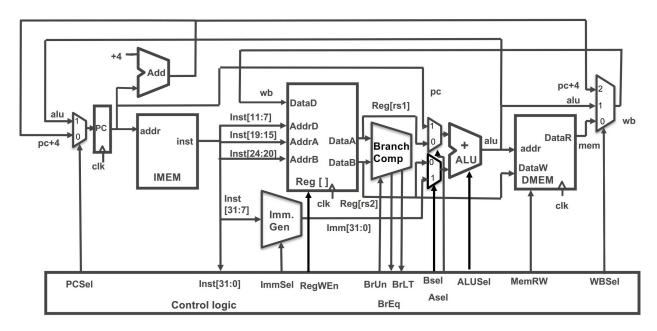
(d) Draw a FSM that outputs 1 when it receives two or more successive '0'.





12. RISC-V Datapath

Here is the datapath we learnt from class:



(a) Assume our single-cycle CPU works in 1Ghz, fill in the two blanks.

Stage	IF	EXE	MEM	WB
Time Cost(ps)	200	350	170	130

Solution: ID 150

(b) Which of following instructions involves all stages of execution?

A. addi

3

B. jalr

C. lw

D. auipc

Solution: C

(c) Assume t3 = 0x8fffffff, t4 = 0x0fffffff. Write down control signals for **blt t3**, **t4**, **label**. Please use * to indicate that what this signal is does not matter.

PCSel	ImmSel	RegWEn	BrUn	BrEq	BrLT	ASel	BSel	ALUSel	MemRW	WBSel

Solution: PCSel = 1 ImmSel = B RegWEn = 0 BrUn = 0 BrEq = 0 BrLT = 1 ASel = 1 BSel = 1 ALUSel = Add MemRW = Read WBSel = *